

Cogging in Fermilab Booster

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Booster

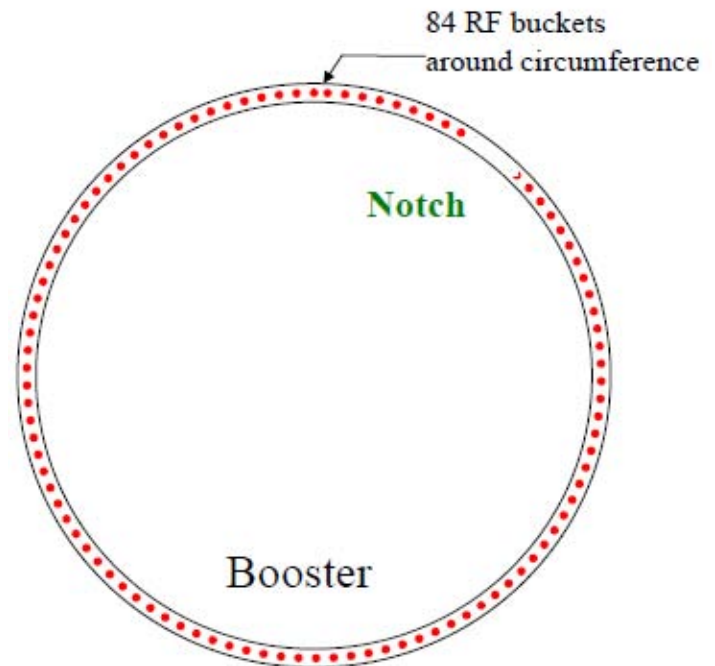
Booster parameters

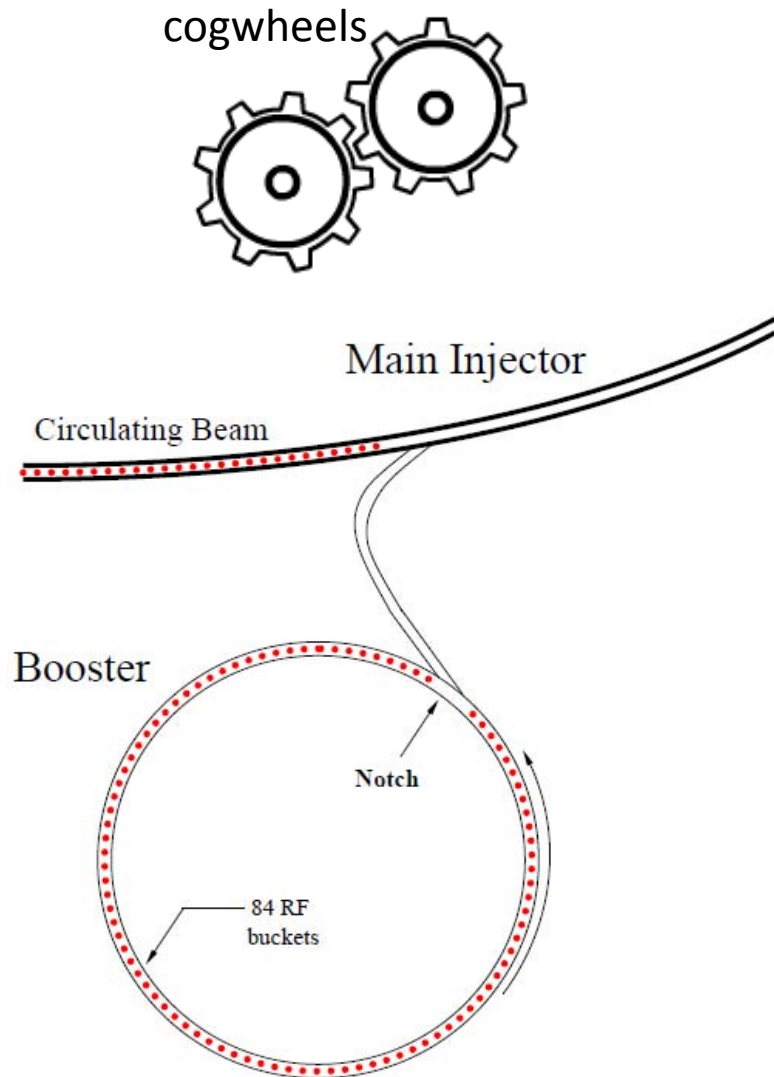
- Diameter.....150 meters
- Injection energy.....400 MeV (kinetic)
- Extraction energy.....8 GeV (kinetic)
- Cycle time.....33 msec
- Harmonic number, h84
- Injection Frequency.....37.77 MHz
- Extraction Frequency.....52.81 MHz
- Typical bunch intensity..... 5×10^{10}



Notching

- Defined:
 - act of using a dedicated kicker magnet in Booster Period 5 to induce orbit distortion on the last 3 bunches in a batch of Booster beam.
- Extraction kicker risetime ≈ 40 ns.
 - Bunch-to-bunch space at the extraction ≈ 20 ns
- Instead of loosing beam at 8 GeV during extraction beam is removed at 400 MeV
 - Reduces energy loss 20x times





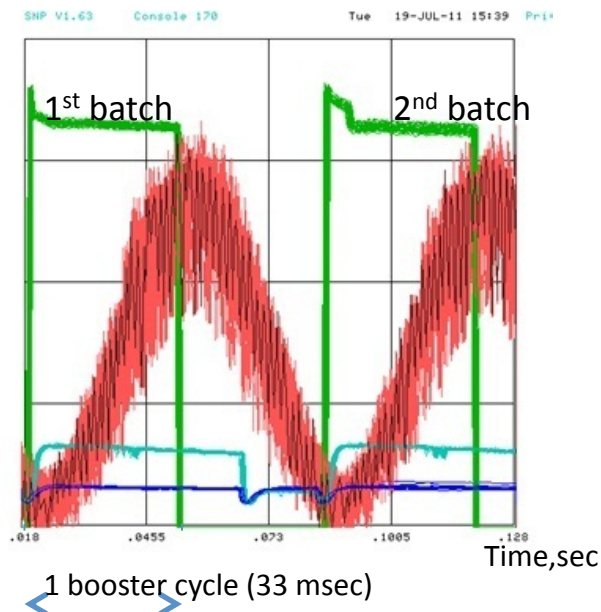
Booster Cogging

- Defined: adjusting the revolution frequency of bunched beam in a synchrotron to correspond to some external frequency
- Extraction:
 - More than 2 batches needed to be extracted to Main Injector
 - Batch in booster should be aligned with the Main Injector beam
- To synchronize Booster and Main Injector procedure to align notch and beam in MI – cogging – is needed.

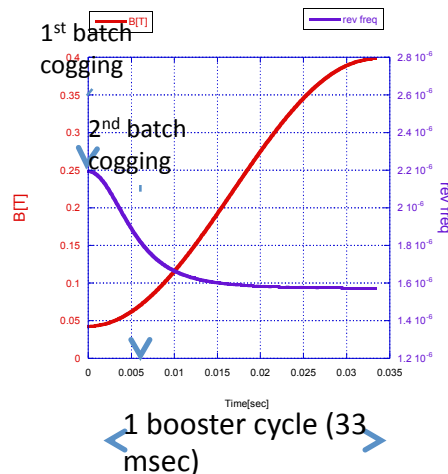
Current state of “Notching” in Booster

Number of
particles in the
beam

Magnetic field



- Notching of the 1st batch is completed as soon as possible:
 - Kicker is synchronized with the beam revolution marker
 - No beam in Main Injector, cogging is not needed for the first batch
- 2nd - 7th batches are notched later
 - Cogging is needed to match beam in MI with the beam being extracted from Booster
 - Notch position moves slower when completed on the higher energy (revolution time changes slower when magnetic field is bigger)



The goal of the research:

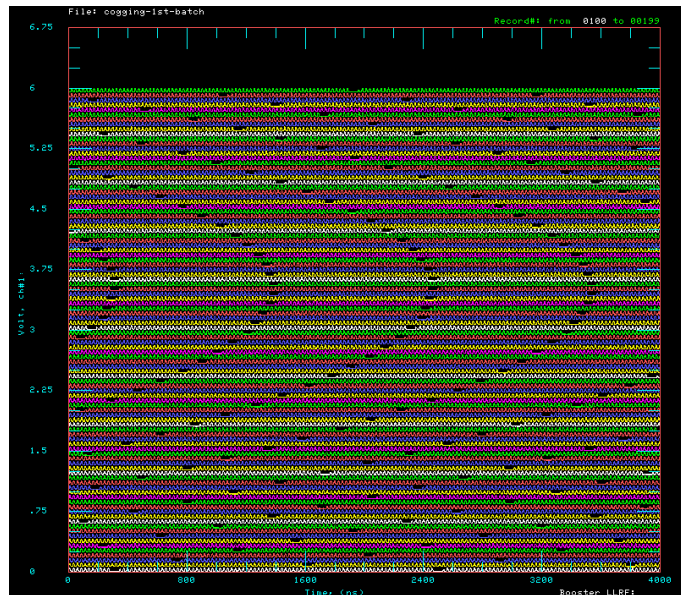
- To decrease energy loss while notching the beam in Booster
- Create notch at lower energy
- Complete cogging with dipole corrector

Task:

1. Get acquainted with longitudinal motion & make simulation
2. Understand the variation of the B field at the injection energy
 - Set up the measurement of the beam signal using wall current monitor
 - Compare experimental results with simulation
 - Calculate total bucket slippage
3. Estimate required B field from dipole corrector

Data acquisition & analysis

Number of trace



Time, nsec

Mountain range plot:

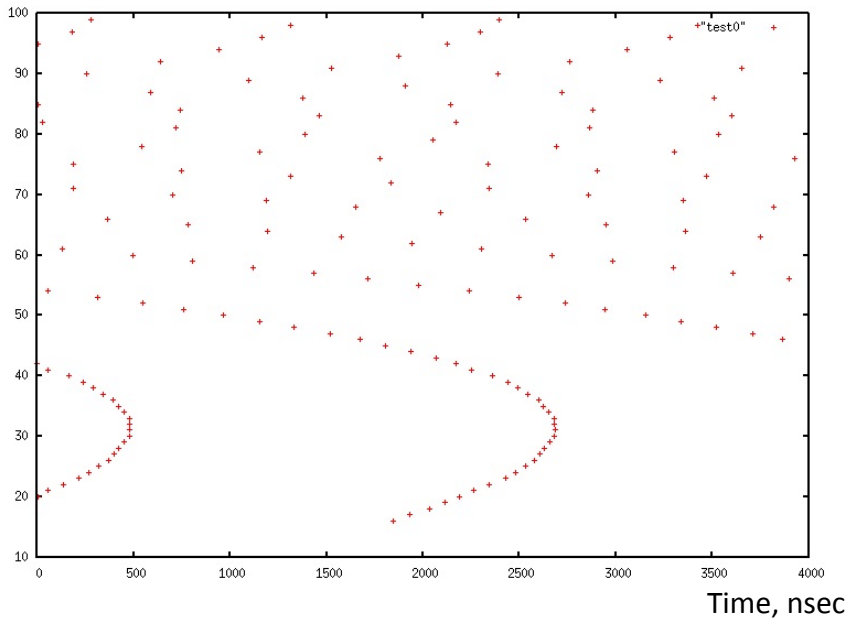
- External trigger starts to collect data with the set frequency
- Data array of the fixed length (10^4 points, 0.4 nsec/point) is taken for each trigger signal
- Different traces are shown on the same plot
- **Revolution time** and corresponding **magnetic field** can be calculated while comparing distance between “gaps”



Analysis & comparison with simulation

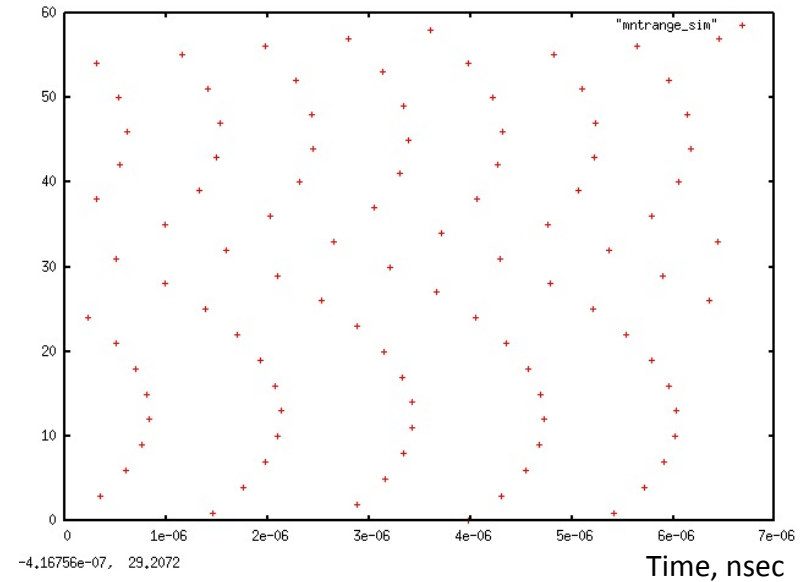
“Gap” position at Mountain
range plot

Number of trace



Measurement

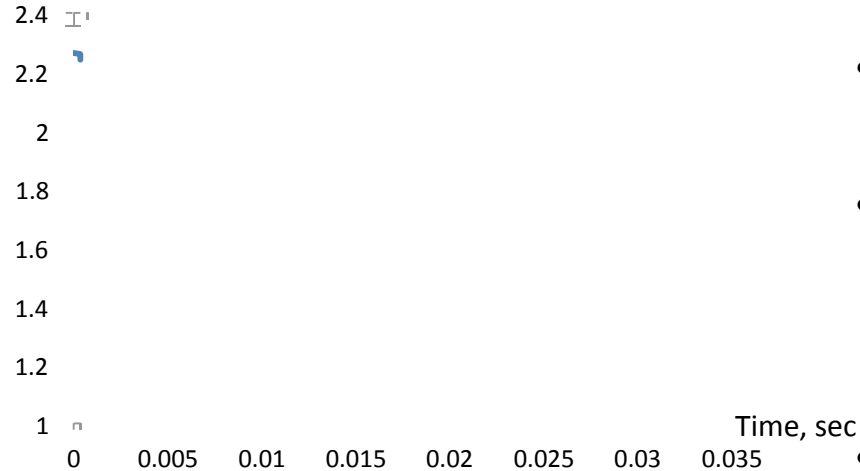
Number of trace



simulation

Simulation

Revolution
time, μsec

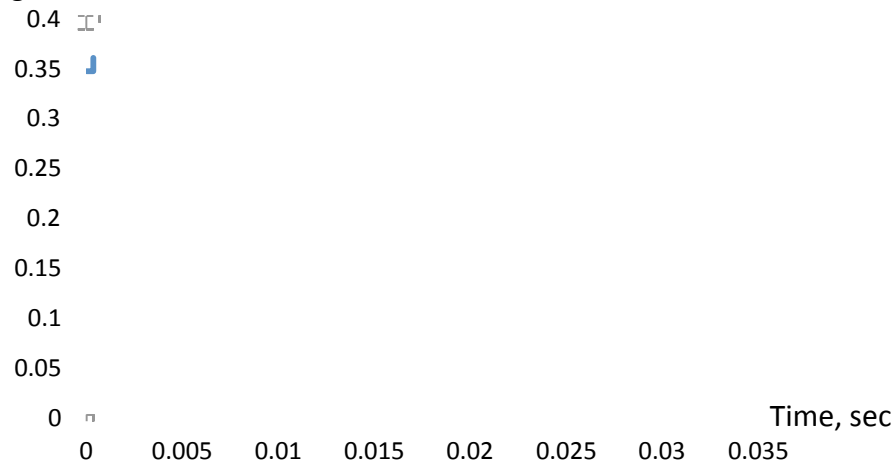


- $E_{\text{inj}} = 400 \text{ MeV}$, $E_{\text{extraction}} = 8 \text{ GeV}$

- The magnetic field in Booster is changing as sin with the frequency of 15Hz

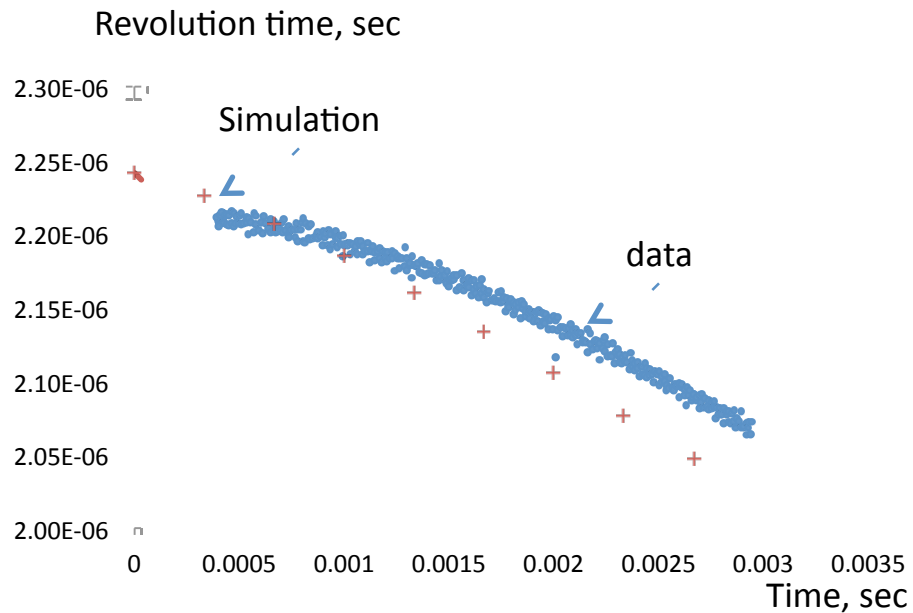
- Revolution time during acceleration can be calculated

Magnetic field, Tesla



Preliminary results

- Bucket slippage can be calculated while comparing revolution time of the real beam and simulation



Summary

1. Got acquainted with longitudinal motion & several simulations on it have been completed
2. Understand the variation of the B field at the injection energy
 - set up the measurement of the beam signal using wall current monitor
 - Compare experimental results with simulation
3. Estimate required B field from dipole corrector

Future plans

- Get more data sets to compare with simulation
- Calculate bucket slippage while notching on lower magnetic field values, i.e. lower energies.
- Continue with how calculated magnetic field corrections could be applied to synchronize “gap” position in Booster with existing beam in Main Injector
- To do measurement with dipole corrector